## TTIC 31230, Fundamentals of Deep Learning

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Early Stopping meets Shrinkage

 $L_1$  Regularization and Sparsity

**Ensembles** 

## Shrinkage meets Early Stopping

Early stopping can limit  $||\Phi||$ .

But early stopping more directly limits  $||\Phi - \Phi_{\text{init}}||$ .

It seems better to take the prior on  $\Phi$  to be

$$p(\Phi) \propto \exp\left(-\frac{||\Phi - \Phi_{\text{init}}||^2}{2\sigma^2}\right)$$

giving

$$\Phi_{t+1} = \Phi_t - \eta \hat{g} - \gamma (\Phi_t - \Phi_{\text{init}})$$

## $L_1$ Regularization

$$p(\Phi) \propto e^{-\lambda||\Phi||_1} \qquad ||\Phi||_1 = \sum_i |\Phi_i|$$

$$\Phi^* = \underset{\Phi}{\operatorname{argmax}} \quad p(\Phi) \prod_i P_{\Phi}(y_i|x_i)$$

$$\Phi^* = \underset{\Phi}{\operatorname{argmin}} \quad \left(\sum_i -\ln P_{\Phi}(y_i|x_i)\right) + \lambda ||\Phi||_1$$

$$\Phi^* = \underset{\Phi}{\operatorname{argmin}} \quad \hat{\mathcal{L}}(\Phi) + \frac{\lambda}{N_{\text{Train}}} ||\Phi||_1$$

## $L_1$ Regularization

$$\Phi^* = \underset{\Phi}{\operatorname{argmin}} \quad \hat{\mathcal{L}}(\Phi) + \frac{\lambda}{N_{\text{Train}}} ||\Phi||_1$$

$$\Phi_i = \eta \left( \hat{g}_i + \frac{\lambda}{N_{\text{Train}}} \operatorname{sign}(\Phi_i) \right)$$

$$\eta = (1 - \mu)B\eta_0$$

### Sparsity

$$\Phi_i = \eta \left( \hat{g}_i + \frac{\lambda}{N_{\text{Train}}} \operatorname{sign}(\Phi_i) \right)$$

For  $\Phi^*$  the gradient of the objective, and hence the average update, must be zero:

$$\Phi_i^* = 0$$
 if  $|g_i| < \lambda/N_{\text{Train}}$ 

$$g_i = -(\lambda/N_{\text{Train}}) \operatorname{sign}(\Phi_i)$$
 otherwise

But in practice  $\Phi_i$  will never be exactly zero.

#### **Ensembles**

Train several models Ens =  $(\Phi_1, \ldots, \Phi_K)$  from different initializations and/or under different meta parameters.

We define the ensemble model by

$$P_{\text{Ens}}(y|x) = \frac{1}{K} \sum_{k} P_{\Phi_k}(y|x) = E_k P_k(y|x)$$

Ensemble models almost always perform better than any single model.

### Ensembles Under Cross Entropy Loss

$$\mathcal{L}(P_{\text{Ens}}) = E_{\langle x, y \rangle \sim \text{Pop}} - \ln P_{\text{Ens}}(y|x)$$

$$= E_{\langle x, y \rangle \sim \text{Pop}} - \ln E_k P_k(y|x)$$

$$\leq E_{\langle x, y \rangle \sim \text{Pop}} E_k - \ln P_k(y|x)$$

$$= E_k \mathcal{L}(P_k)$$

### Ensembles Under Cross Entropy Loss

It is important to note that

$$-\ln E_k P_k(y|x) \le E_k - \ln P_k(y|x)$$

for each individual pair  $\langle x, y \rangle$ .

$$\forall z \ f(z) \leq g(z)$$
 is stronger than  $(E_z \ f(z)) \leq (E_z \ g(z))$ .

This may explain why in practice an ensemble model is typically better than any single component model.

# $\mathbf{END}$